

# Periodic Positive Solutions for a Delay Nonlinear Differential Equation with Piecewise Constant Arguments

GENQIANG WANG

Department of Computer Science  
Guangdong Polytechnic Normal University  
Guangzhou, Guangdong 510665, P.R. China

BICHENG YANG

Department of Mathematics, Guangdong College of Education  
Guangzhou, Guangdong 510303, P.R. China  
[bcyang@public.guangzhou.gd.cn](mailto:bcyang@public.guangzhou.gd.cn)

L. DEBNATH

Department of Mathematics, University of Texas—Pan American  
Edinburg, TX 78539-2999, U.S.A.  
[debnath1@panam.edu](mailto:debnath1@panam.edu)

(Received May 2003; revised and accepted June 2004)

**Abstract**—Using a fixed-point theorem in cone, existence criteria are proved for the periodic positive solutions of a delay differential equation with piecewise constant arguments. Several examples concerning biological models for the survival of red blood cells are given. © 2004 Elsevier Ltd. All rights reserved.

**Keywords**—Differential equation, Piecewise constant argument, Periodic positive solution, Cone, Fixed-point theorem.

## 1. INTRODUCTION

Considerable attention has been given to delay differential equations with piecewise constant arguments by several authors including Cooke and Wiener [1], Shah and Wiener [2], and Aftabizadeh *et al.* [3]. This class of differential equations has useful applications in biomedical models of disease that have been developed by Busenerg and Cooke [4]. Studies of such equations were motivated by the fact that they represent a hybrid of discrete and continuous dynamical systems and combine the properties of both differential and differential-difference equation.

On the other hand, properties and solutions of delay differential equations with piecewise constant arguments and piecewise constant time delay have received considerable attention by several authors including Wiener [5], Cooke and Wiener [6], Wiener and Cooke [7], Wiener and

---

Authors express grateful thanks to referees for suggesting some corrections and improvements. The work of the third author is partially funded by the Faculty Research Council of the University of Texas—Pan American.

Debnath [8,9], Gopalsamy *et al.* [10], Lin and Wang [11], Papaschinopoulos and Schinas [12], Huang [13], Shen and Stavroulakis [14], and Wiener and Heller [15].

Carvalho and Wiener [16] considered periodic solutions of the first-order differential equation with piecewise constant argument

$$x'(t) = ax(t)(1 - x([t])), \quad (1.1)$$

where  $a$  is constant and  $[\cdot]$  is the greatest integer function. As mentioned by Cooke and Wiener [17], equation (1.1) may be treated as semidiscretization of the ordinary logistic equation and solutions of (1.1) exhibit a wide variety of properties of interest.

In this paper, we consider a more general equation than (1.1), in the form

$$x'(t) = a(t)x(t) + f(t, x([t])), x([t-1]), \dots, x([t-k]), x([t]), \quad (1.2)$$

and

$$x'(t) = a(t)x(t) - f(t, x([t])), x([t-1]), \dots, x([t-k]), x([t]), \quad (1.3)$$

where  $a(t) \in C(R)$  and  $f(t, x_0, \dots, x_{k+1})$  is a periodic function with a period  $\omega$ ,  $f(t, x_0, \dots, x_k, x_{k+1}) \in C(R \times [0, \infty)^{k+2})$ .

The main objective of this paper is to prove several existence criteria for  $\omega$ -periodic positive solutions of equation (1.2) or (1.3) by using the fixed-point theorem in a cone due to Krasnosel'skii (see [18]).

We adopt the same definition for a solution of (1.2) or (1.3) as given by Aftabizadeh *et al.* [3]. By a solution of (1.2) or (1.3), we mean a function  $y(t)$  which is defined on the set  $S = \{-k, -k+1, \dots, 0\} \cup [0, \infty)$  and this function  $y(t)$  satisfies the following conditions:

- (i)  $y(t) = D_i$  ( $i = 0, -1, \dots, -k$ ), where  $D_i$  ( $i = 0, -1, \dots, -k$ ) is initial data;
- (ii)  $y(t)$  is continuous on  $[0, \infty)$ ;
- (iii) the derivative  $y'(t)$  exists at each point  $t \in [0, \infty)$ , with the possible exception of the point  $t \in [0, \infty)$ , where one-sided derivative exists;
- (iv) equation (1.2) or (1.3) is satisfied on each interval  $[n, n+1)$  with integral endpoints.

We also state the fixed-point theorem due to Krasnosel'skii (see [18]) in the following form.

**THEOREM 1.1.** Suppose  $K$  is a cone in Banach space  $X$ ,  $\Omega_1$  and  $\Omega_2$  are two bounded open sets in  $X$  such that  $\theta \in \Omega_1$ , and  $\bar{\Omega}_1 \subset \Omega_2$  and  $\Phi : K \rightarrow K$  is a completely continuous operator. Further, suppose that any one of the following conditions is satisfied:

- (i) for each  $u \in K \cap \partial\Omega_1$ ,  $\|\Phi u\| \leq \|u\|$ , and for each  $u \in K \cap \partial\Omega_2$ ,  $\|\Phi u\| \geq \|u\|$ ;
- (ii) for each  $u \in K \cap \partial\Omega_1$ ,  $\|\Phi u\| \geq \|u\|$ , and for each  $u \in K \cap \partial\Omega_2$ ,  $\|\Phi u\| \leq \|u\|$ ;

where  $\partial\Omega_1$  and  $\partial\Omega_2$  represent the boundary of  $\Omega_1$  and  $\Omega_2$ , respectively. Then  $\Phi$  has a fixed point  $u_0 \in K \cap (\bar{\Omega}_2 \setminus \Omega_1)$ .

The notation  $x \rightarrow 0$  denotes that  $x_i$  ( $i = 0, \dots, k, k+1$ ) altogether tend to 0, and  $x \rightarrow \infty$  denotes that all  $x_i$  ( $i = 0, \dots, k+1$ ) tend to infinity.

We use the following conditions. Let  $\alpha_i$  ( $i = 0, \dots, k+1$ ) be nonnegative numbers and  $\sum_{i=0}^{k+1} \alpha_i = 1$  such that

(H<sub>1</sub>)

$$\overline{\lim}_{x \rightarrow 0^+} \max_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = 0$$

and

$$\underline{\lim}_{x \rightarrow \infty} \min_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = \infty;$$

(H<sub>2</sub>)

$$\lim_{x \rightarrow 0^+} \min_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = \infty$$

and

$$\overline{\lim}_{x \rightarrow \infty} \max_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = 0.$$

## 2. MAIN RESULTS

**THEOREM 2.1.** *If condition (H<sub>1</sub>) is satisfied, then equation (1.2) has an  $\omega$ -periodic positive solution.*

**THEOREM 2.2.** *If condition (H<sub>2</sub>) is satisfied, then equation (1.2) has an  $\omega$ -periodic positive solution.*

**THEOREM 2.3.** *If condition (H<sub>1</sub>) is fulfilled, then equation (1.3) has an  $\omega$ -periodic positive solution.*

**THEOREM 2.4.** *If condition (H<sub>2</sub>) is satisfied, then equation (1.3) has an  $\omega$ -periodic positive solution.*

We only give proofs of Theorem 2.1 and 2.2. Theorems 2.3 and 2.4 can be proved similarly.

Let  $X$  be the Banach space of all functions  $x = x(t)$  which are defined on  $\{-k, \dots, 0\} \cup [0, \infty)$  and continuous on  $[0, \infty)$  such that  $x(t + \omega) = x(t)$  for  $t \in \{-k, \dots, 0\} \cup [0, \infty)$ , endowed with the norm  $\|x\| = \max_{0 < t < \omega} |x(t)|$ . If

$$K = \{x \in X, x(t) \geq \sigma \|x\|\},$$

where  $\sigma = \exp(-\int_0^\omega a(\nu) d\nu)$ , and  $a(x)$  is defined before, then  $K$  is a cone in  $X$ . We next set

$$G(t, s) = \frac{\exp\left(\int_t^s a(\nu) d\nu\right)}{\exp\left(\int_0^\omega a(\nu) d\nu - 1\right)}. \quad (2.1)$$

It is easy to see that  $x(t)$  is an  $\omega$ -periodic positive solution of (1.2) if and only if  $x(t)$  is an  $\omega$ -periodic positive solution of the following equation:

$$x(t) = \int_t^{t+\omega} G(t, s) f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) ds. \quad (2.2)$$

If we define the mapping  $\Phi : X \rightarrow X$  by

$$(\Phi x)(t) = \begin{cases} \int_t^{t+\omega} G(t, s) f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) ds, & t \geq 0, \\ (\Phi x)(i - i\omega), & t = i \quad (i = 0, -1, \dots, -k), \end{cases} \quad \omega < 1, \quad (2.3)$$

then  $\Phi$  is completely continuous, and for  $x \in K$ ,

$$\begin{aligned} \|\Phi x\| &\leq G(t, t + \omega) \int_0^\omega f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) ds, \\ &= G(0 + \omega) \int_0^\omega f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) ds. \end{aligned} \quad (2.4)$$

Thus,

$$\begin{aligned}
 (\Phi x)(t) &\geq G(t, t) \int_0^\omega f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) \, ds, \\
 &= G(0, 0) \int_0^\omega f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) \, ds, \\
 &\geq \frac{G(0, 0)}{G(0, \omega)} \|\Phi x\| = \sigma \|\Phi x\|, \quad t \geq 0.
 \end{aligned} \tag{2.5}$$

Noting that  $i - i\omega \geq 0$ , ( $\omega < 1$ ) for  $i = 0, -1, \dots, -k$ , by (2.3) and (2.5) and the definition of  $K$ , we have

$$(\Phi x)(t) = (\Phi x)(i - i\omega) \geq \sigma \|x\|, \quad t = i, \quad (i = 0, -1, \dots, -k). \tag{2.6}$$

It follows from (2.5) and (2.6) that

$$\Phi x \in K, \quad \text{that is,} \quad \Phi K \subset K.$$

PROOF OF THEOREM 2.1. First of all, we set a positive number  $\varepsilon$  such that  $G(0, \omega)\omega\varepsilon < 1$ , it follows from  $(H_1)$  that

$$\overline{\lim}_{x \rightarrow 0^+} \max_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = 0.$$

Then there exists a  $\rho_1 > 0$  such that

$$f(t, x_0, \dots, x_k, x_{k+1}) \leq \varepsilon \prod_{i=0}^{k+1} |x_i|^{\alpha_i}, \quad |x_i| \leq \rho_1, \quad (i = 0, 1, \dots, k+1). \tag{2.7}$$

In view of (2.4) and (2.7), for each  $x \in K$  and  $\|x\| = \rho_1$ , it turns out that

$$\begin{aligned}
 \|\Phi x\| \max_{0 \leq t \leq \omega} |(\Phi x)(t)| &\leq G(0, \omega) \int_0^\omega f(s, x[s]), x([s-1]), \dots, x([s-k]), x([s]) \, ds, \\
 &\leq G(0, \omega)\varepsilon \int_0^\omega |x(s)|^{\alpha_{k+1}} \prod_{i=0}^k |x([s-i])|^{\alpha_i} \, ds, \\
 &\leq \frac{G(0, 0)}{G(0, \omega)} \varepsilon \omega \|x\| < \|x\|.
 \end{aligned} \tag{2.8}$$

In other words, for each  $x \in K \cap \partial\Omega_1$ ,  $\|\Phi x\| < \|x\|$ , where  $\Omega_1 = \{x \in X \mid \|x\| < \rho_1\}$ . Let  $M$  be a positive number such that  $G(0, 0)\omega\sigma M > 1$ . It follows from  $(H_1)$  that

$$\underline{\lim}_{x \rightarrow \infty} \min_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = \infty.$$

Then there exist  $\rho_2 > 0$  and  $\rho_2 > \rho_1$ , such that

$$f(t, x_0, \dots, x_k, x_{k+1}) \geq M \prod_{i=0}^{k+1} |x_i|^{\alpha_i}, \quad |x_i| \geq \frac{\rho_2}{\sigma}, \quad (i = 0, 1, \dots, k+1). \tag{2.9}$$

Using (2.3) and (2.9), for each  $x \in K$  and  $\|x\| = \rho_2$ , we have

$$\begin{aligned}
 \|\Phi x\| &= \max_{0 \leq t \leq \omega} |(\Phi x)(t)| \geq G(0, 0) \int_0^\omega f(s, x([s]), x([s-1]), \dots, x([s-k]), x([s]), \, ds \\
 &\geq G(0, 0)M \int_0^\omega |x(s)|^{\alpha_{k+1}} \prod_{i=0}^k |x([s-i])|^{\alpha_i} \, ds \\
 &\geq G(0, 0)M\sigma \|x\| > \|x\| = \rho_2.
 \end{aligned} \tag{2.10}$$

That is, for each  $x \in K \cap \partial\Omega_2$ ,  $\|\Phi x\| > \|x\|$ , where  $\Omega_2 = \{x \in X \|x\| < \rho_2\}$ . It follows from relations (2.8), (2.10), and Theorem 1.1 with  $\Omega_1 \subset \Omega_2$  that the mapping  $\Phi$  has a fixed point  $x_0 \in K \cap (\overline{\Omega}_2 \setminus \Omega_1)$ . In view of definitions of  $\Omega_1$  and  $K$ , we have  $x(t) \geq \sigma \|x\| \geq \sigma \rho_1 > 0$ . Thus,  $x(t)$  is an  $\omega$ -periodic positive solution of (1.2). The proof of Theorem 2.1 is complete.

PROOF OF THEOREM 2.2.. Let  $M$  be a positive number such that  $G(0, 0)\omega\sigma M > 1$ . It follows from  $(H_2)$  that

$$\lim_{x \rightarrow 0} \min_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = \infty.$$

Then there exists a  $\rho_1 > 0$  such that

$$f(t, x_0, \dots, x_k, x_{k+1}) \geq M \prod_{i=0}^{k+1} |x_i|^{\alpha_i}, \quad |x_i| \leq \rho_1, \quad (i = 0, 1, \dots, k+1). \quad (2.11)$$

By (2.3) and (2.11), for each  $x \in K$  and  $\|x\| = \rho_1$ , we have the following inequality:

$$\begin{aligned} \|\Phi x\| &= \max_{0 \leq t \leq \omega} |(\Phi x)(t)| \geq G(0, 0) \int_0^\omega f(s, x([s]), x([s-1]), \dots, x([s-k]), x([s])) ds \\ &\geq G(0, 0)M \int_0^\omega |x(s)|^{\alpha_{k+1}} \prod_{i=0}^k |x([s-i])|^{\alpha_i} ds \\ &\geq G(0, 0)M\omega\sigma \|x\| > \|x\| = \rho_1. \end{aligned} \quad (2.12)$$

That is, for each  $x \in K \cap \partial\Omega_1$ ,  $\|\Phi x\| > \|x\|$ , where  $\Omega_1 = \{x \in X \|x\| < \rho_1\}$ . Let  $\varepsilon > 0$  such that  $G(0, \omega)\omega\varepsilon > 1$ . It follows from  $(H_2)$  that

$$\overline{\lim}_{x \rightarrow \infty} \max_{0 \leq t \leq \omega} \frac{f(t, x_0, \dots, x_k, x_{k+1})}{\prod_{i=0}^{k+1} |x_i|^{\alpha_i}} = 0.$$

Hence, there exist  $\rho_2 > \rho_1 > 0$  such that

$$f(t, x_0, \dots, x_k, x_{k+1}) \leq \varepsilon \prod_{i=0}^{k+1} |x_i|^{\alpha_i}, \quad |x_i| \geq \frac{\rho_2}{\sigma}, \quad (i = 0, 1, \dots, k+1). \quad (2.13)$$

By (2.4) and (2.13), for each  $x \in K$  and  $\|x\| = \rho_2$ , we have the following inequality:

$$\begin{aligned} \|\Phi x\| &= \max_{0 \leq t \leq \omega} |(\Phi x)(t)| \leq G(0, \omega) \int_0^\omega f(s, x([s]), x([s-1]), \dots, x([s-k]), x([s])) ds \\ &\leq G(0, \omega)\varepsilon \int_0^\omega |x(s)|^{\alpha_{k+1}} \prod_{i=0}^k |x([s-i])|^{\alpha_i} ds \\ &\leq G(0, \omega)\varepsilon\omega \|x\| < \|x\|. \end{aligned} \quad (2.14)$$

That is, for each  $x \in K \cap \partial\Omega_2$ ,  $\|\Phi x\| < \|x\|$ , where  $\Omega_2 = \{x \in X \|x\| < \rho_2\}$ . It follows from relations (2.12), (2.14), and Theorem 1.1 with  $\Omega_1 \subset \Omega_2$  that the mapping  $\Phi$  has a fixed point  $x_0 \in K \cap (\overline{\Omega}_2 \setminus \Omega_1)$ . In view of definitions of  $\Omega_1$  and  $K$ , we have  $x(t) \geq \sigma \|x\| \geq \sigma \rho_1 > 0$ . Thus,  $x(t)$  is an  $\omega$ -periodic positive solution of (1.2). The proof of Theorem 2.2 is complete.

### 3. EXAMPLES

EXAMPLE 1. The model for the survival of red blood cells is given in [19–21] of the form

$$x'(t) = -a(t)x(t) + b(t)\exp[x(t - \tau(t))], \quad (3.1)$$

where  $x(t)$  denotes the number of red blood cells at time  $t$ ,  $a(t)$  is the probability of death of a red cell,  $b(t)$  is related to the production of red blood cells, and  $\tau(t)$  is the time required to produce a red blood cell. Following Kocic and Ladas [21], we consider a semidiscrete model, for the survival of red blood cells in an animal which satisfies the equation

$$x'(t) = -a(t)x(t) + b(t)\exp(x([t - k])), \quad t \geq 0, \quad (3.2)$$

where  $a(t)$  and  $b(t)$  belong to  $C(R)$ ,  $a(t + \omega) = a(t)$  and  $b(t + \omega) = b(t)$ . Let  $f(t, x) = b(t)\exp(-x)$ . We see that

$$\lim_{x \rightarrow 0^+} \min_{0 \leq t \leq \omega} \frac{f(t, x)}{|x|} = \infty \quad \text{and} \quad \overline{\lim}_{x \rightarrow \infty} \max_{0 \leq t \leq \omega} \frac{f(t, x)}{|x|} = 0.$$

Using Theorem 2.2 gives that (3.2) has an  $\omega$ -periodic positive solution.

EXAMPLE 2. The model for the generation of red blood cells in an animal is described in [22, 23] of the form

$$x'(t) + a(t)x(t) = \frac{b(t)}{1 + (x(t - \tau(t)))^n}. \quad (3.3)$$

We follow Kocic and Ladas [21] to study solutions of discrete analogue of (3.3).

We consider a semidiscrete model for the generating of red blood cells in an animal that satisfies the equation

$$x'(t) = -a(t)x(t) + \frac{b(t)}{1 + (x([t - k]))^n}, \quad t \geq 0, \quad (3.4)$$

where  $n$  is a positive integer,  $a(t)$  and  $b(t)$  belong to  $C(R)$ ,  $a(t + \omega) = a(t)$  and  $b(t + \omega) = b(t)$ . Suppose  $f(t, x) = b(t)/(1 + |x|^n)$ . We obtain

$$\lim_{x \rightarrow 0^+} \min_{0 \leq t \leq \omega} \frac{f(t, x)}{|x|} = \infty \quad \text{and} \quad \overline{\lim}_{x \rightarrow \infty} \max_{0 \leq t \leq \omega} \frac{f(t, x)}{|x|} = 0.$$

Using Theorem 2.2 gives that (3.2) has an  $\omega$ -periodic positive solution.

EXAMPLE 3. Making reference to [24–26], we state a model equation for generation of a biological model in the form

$$x'(t) = x(t) \left[ a(t) - \sum_{i=1}^n b_i(t)(x(t - \tau_i(t))) \right]. \quad (3.5)$$

We consider a semidiscrete biological model which satisfies the equation

$$x'(t) = x(t) \left( a(t) - \prod_{i=0}^k \frac{x([t - i])}{b(t)} \right), \quad (3.6)$$

where  $k$  is a positive integer,  $a(t)$  and  $b(t)$  belong to  $C(R)$ ,  $a(t + \omega) = a(t)$  and  $b(t + \omega) = b(t)$ . Let  $f(t, x_0, \dots, x_k, x_{k+1}) = \prod_{i=0}^{k+1} |x_i|/(b(t))^k$ , and set  $\alpha_1 = 0$  ( $i = 0, 1, \dots, k$ ),  $\alpha_{k+1} = 1$ . Then  $\sum_{i=0}^{k+1} \alpha_i = 1$ . It is easy to see that condition  $(H_1)$  is satisfied. Using Theorem 2.3 leads to the fact that (3.5) has an  $\omega$ -periodic positive solution.

EXAMPLE 4. We consider a semidiscrete biological model which satisfies the equation

$$x'(t) = x(t) \left( a(t) - \sum_{i=0}^k b_i(t)x([t - i]) \right), \quad (3.7)$$

where  $k$  is a positive integer,  $a(t)$  and  $b(t)$  belong to  $C(R)$ ,  $a(t + \omega) = a(t)$  and  $b_i(t + \omega) = b_i(t)$ , ( $i = 0, 1, \dots, k$ ). By Theorem 2.3, we know that (3.7) has an  $\omega$ -periodic positive solution.

## REFERENCES

1. K.L. Cooke and J. Wiener, Retarded differential equations with piecewise constant delays, *Journal of Mathematical Analysis and Applications* **99**, 265–297, (1984).
2. S.M. Shah and J. Wiener, Advanced differential equations with piecewise constant argument deviations, *International Journal of Mathematics and Mathematical Sciences* **6**, 671–703, (1983).
3. A.R. Aftabizadeh, J. Wiener and J. Xu, Oscillatory and periodic solutions of delay differential equations with piecewise constant argument, *Proceedings American Mathematical Society* **99**, 673–679, (1987).
4. S. Busenerg and K.L. Cooke, Models of vertically transmitted diseases with sequential-continuous dynamics, In *Nonlinear Phenomena in Mathematical Sciences*, (Edited by V. Lakshmikantham), pp. 179–187, Academic Press, New York, (1982).
5. J. Wiener, Boundary-value problems for partial differential equations with piecewise constant delay, *International Journal of Mathematical and Mathematical Sciences* **14**, 301–321, (1991).
6. K.L. Cooke and J. Wiener, An equation alternately of retarded and advanced type, *Proceedings American Mathematical Society* **99**, 726–732, (1987).
7. J. Wiener and K.L. Cooke, Oscillations in systems of differential equations with piecewise constant argument, *Journal of Mathematical Analysis and Applications* **137**, 221–239, (1989).
8. J. Wiener and L. Debnath, Partial differential equations with piecewise constant delay, *International Journal of Mathematics and Mathematical Sciences* **14**, 485–496, (1991).
9. J. Wiener and L. Debnath, The Fourier method for partial differential equations with piecewise constant delay, In *Contemporary Mathematics, Volume 129*, (Edited by J.R. Graef and J.K. Hale), pp. 339–346, American Mathematical Society, Providence, RI, (1992).
10. K. Gopalsamy, M.R.S. Kulenovic and G. Ladas, On a logistic equation with piecewise constant arguments, *Differential and Integral Equations* **4**, 215–223, (1991).
11. L.C. Lin and G.Q. Wang, Oscillatory and asymptotic behavior of first order nonlinear differential equations with retarded argument  $[t]$ , *Chinese Science Bulletin* **36**, 889–891, (1991).
12. G. Papaschinopoulos and J. Shinas, Existence stability and oscillation of the solutions of first order neutral equation with piecewise constant argument, *Applied Analysis* **44**, 99–111, (1992).
13. Y.K. Huang, Oscillations and asymptotic stability of solutions of first order neutral equations with piecewise constant argument, *Journal of Mathematical Analysis and Applications* **149**, 99–111, (1992).
14. J.H. Shen and I.P. Stravroulakis, Oscillatory and non-oscillatory delay equations piecewise constant argument, *Journal of Mathematical Analysis and Applications* **248**, 385–401, (1992).
15. J. Wiener and W. Heller, Oscillatory and periodic solutions to a diffusion equation of neutral type, *International Journal of Mathematical and Mathematical Science* **22**, 313–348, (1999).
16. L.A.V. Carvalho and J. Wiener, A nonlinear equation with piecewise continuous argument, *Differential and Integral Equations* **1**, 359–367, (1988).
17. K.L. Cooke and J. Wiener, A survey of differential equations with piecewise constant argument, In *Lecture Notes in Mathematics, Volume 1475*, pp. 1–15, Springer Verlag, Berlin, (1991).
18. D.J. Guo, *Nonlinear Functional Analysis*, (in Chinese), Science Technological Publishers, Shandong, (1985).
19. S.N. Chow, Existence of periodic solutions of autonomous functional differential equation, *Journal of Differential Equations* **15**, 75–78, (1974).
20. M. Wazewska-Czyzwska and A. Lasota, Mathematical problems of the dynamics of the red blood cells system, *Annals of the Polish Math. Sec. Series III, Appl. Math.* **17**, 23–40, (1988).
21. V.L. Kocic and G. Ladas, *Global Behavior of Nonlinear Difference Equations of Higher Order with Applications*, Kluwer Academic, Dordrecht, (1993).
22. M. Mackey and L. Glass, Oscillations and chaos in physiological control systems, *Science* **197**, 287–289, (1977).
23. J. Mallet-Paret and R. Nussbaum, Global continuation and asymptotic behavior for periodic solutions of a differential delay equation, *Ann. Di. Math. Pured. Appl.* **145**, 33–128, (1986).
24. K. Gopalsamy, *Stability and Oscillations in Delay Differential Equations of Population Dynamics*, Kluwer Academic, Boston, (1992).
25. Y. Kuang, *Delay Differential Equations with Applications in Population Dynamics*, Kluwer Academic, Boston, (1993).
26. S. Lenhart and C. Travis, Global stability of a biological model with time delay, *Proceedings American Mathematical Society* **96**, 75–78, (1986).